Program

8:30-9:00: Welcome
9:00-10:00: Gordon Cheng (TU München)
   Robots doing their best without speech in Human Environments
10:00-11:00: Posters around a coffee
11:00-12:00: Ludovic Righetti (MPI Tuebingen)
   Exploiting contact interactions for robust manipulation & locomotion skills
12:00-13:30: Buffet lunch
13:30-14:00: Radu Horaud (Perception/INRIA & LJK)
   Audio-Visual Scene Analysis for Human-Robot Interaction
14:00-14:30: Damien Pellier (MAGMA/LIG-Lab)
   Robot Programming by Demonstration in Cobotic Environment
14:30-15:00: Coffee break
15:00-15:30: Jose-Ernesto Gomez-Balderas (AGPIG/GIPSA-Lab)
   Mini-UAV teleoperation in a structured environment
15:30-16:00: Jérôme Maisonnasse (FAB-Lab/MSTIC & LIG-Lab)
   Fablab & robotics
16:00-16:30 Round table & conclusions